

《水质监测用无人艇技术要求（试行）》
（征求意见稿）

编制说明

2017-26

1	1
1.1	1
1.2	1
2	3
3	3
3.1	3
3.2	4
3.3	4
3.4	7
3.5	7
4	7
4.1	7
4.2	8
4.3	8
5	8
5.1	8
5.2	8
6	8
6.1	8
6.2	10
6.3	10
6.4	11
6.5	12
6.6	17
6.7	22
6.8	22
6.9	23
6.10	23
7	24
8	25
9	26

1

1.1

2017

2017

2017 413

2017-26

1.2

1.2.1

2017 6

2017

1

“ ”

1.2.2

2017 4 ~2017 10

ISO

OECD ASTM

ISO 15839:2003

-

Water quality -- On-line sensors/analysing equipment for water -- Specifications and performance tests ASTM D3864 – 12 Standard Guide for

On-Line Monitoring Systems for Water Analysis OECD 236

Nanosystems for Water Quality Monitoring and Purification

HJ 731-2014

HJ 915-2017

1.2.3

2017 11 14

1

2

3

2018 2 1

1 : 2 :
3

1.2.4

2018 3 ~8

1.2.5

2018 8 29 ~30

2018 11 10 ~22

3

2019 6 ~10

1.2.6

2020 5 9

2020 6 23

1

2

3 HJ 168 HJ 565

2

3

3.1

vehicles USV Unmanned surface vehicles Autonomous surface

1898 . “
”
20 50
20 90
21

2000 MIT “Auto Cat”
2003 “Kan-Chan”

“Springer”

200

“SeaFly”

”“ 0 ”“ ”“ ”“ 3 ”“ 5 ”“ ”

3.2

2019

1

中国地图



1

3.3

8.12

2016	5	~6			8		
	7		1	7	72 km		8.8 km ²
		DO		(NH ₃ -N)	ORP		

	$p(\text{DO})/(\text{m/L}^{-1})$			ORP/mV			/NTU			$p(\text{NH}_3\text{-N})/(\text{m/L}^{-1})$		
						/%			/%			/%
1	3.98	4.07	-0.09	190.32	180.6	5.38	29.12	35.2	-17.27	1.28	1.62	-20.99
2	4.28	4.65	-0.37	191.65	181.7	5.48	0	30.5	-100.00	1.581	2.04	-22.50
3	1.86	1.95	-0.09	158.24	172.5	-8.27	0	80.3	-100.00	2.56	3.11	-17.68
4	2.75	2.93	-0.18	159.84	173.6	-7.93	0	65.4	-100.00	2.259	2.86	-21.01
5	7.02	6.85	0.17	197.07	190.8	3.29	0	16.5	-100.00	3.36	3.94	-14.72
6	6.26	6.21	0.05	202.79	204.6	-0.88	0	25.3	-100.00	3.58	3.98	-10.05
7	6.20	6.11	0.09	138.22	126.4	9.35	195.95	23.1	748.27	3.608	4.10	-12.00
8	6.80	6.54	0.26	138.25	130.8	5.70	0	20.4	-100.00	3.849	4.21	-8.57
9	7.36	6.93	0.43	180.82	178.7	1.19	0	19.6	-100.00	5.401	4.89	10.45
10	5.81	6.13	-0.32	150.3	151.3	-0.66	49.1	31.1	57.88	5.307	4.75	11.73

3
4
5

4.2

1
2
3
4

4.3

HJ 168

1

2

3

4

2

5

5.1

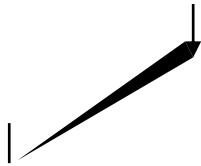
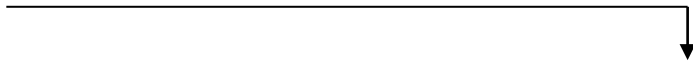
200 kg

5.2

6

6.1

“ 200 kg ”



200 kg

200 kg

6.2

14

GB/T 14581

HJ/T 91
HJ/T 354

HJ 494

HJ/T 372

CCS 2018

1

GB 4943.1

GB 17799.4

GB/T 13384

GB/T 14581

GB 6920 pH

GB 13195

GB 4943.1

1

GB 17799.4

GB/T 13384

HJ 354

COD_{Cr} NH₃-N

HJ 91

HJ/T 372

HJ 494

HJ 506

HJ 535

HJ 897

a

CCS 2018

6.3

- 1 unmanned surface vehicle
 unmanned surface vehicle USV

- 2 USV for water quality monitoring

- 3 platform

- 4 mission loading

- 5 water sampling

- 6 monitoring

- 7 in-situ monitoring

- 8 communication system

- 9 control system
 /

- 10 remote control
 /

- 11 autonomous sailing

- 12 display and control base

- 13 remote controller

6.4

1

1 m/s 3 h

10 km

10 km

50 km

2

- a) 2.5 m
- b) $\pm 1^\circ$
- c) $\pm 1^\circ$ $0^\circ \sim 15^\circ$

CCS

MSC.112 73

GPS

SJ/T 11420-2010 GPS

3

- a)
- b)
 - 2 km
 - 5 km
- c)
 - 9600
 - 4 Mbps
- d) 1km

4

CCS

“

” UN38.3

- a)
- b)
- c)

•

•

•

300

•

UN38.3

IP67

5

CCS

“ ” “ ”

a)

b)

c)

10 m

d)

e)

f)

g)

h) IP66

6

CCS

“ ” “ ”

2

”

A.

a

•

•

b

•

•

c

•

•

•

•

•

•

•

d

e

f

/
 •
 /
 •
 •
 B.
 a
 •
 •
 •
 •
 •
 •
 b)
 •
 •
 •
 •
 7
 A.

GPS/

HJ/T 372-2007

HJ/T 91-2002 2

2

1		G		24 h	1 L
2		G		24 h	500 ml
3		P		14 d	250 ml
4		G		24 h	1 L
5		P		14 d	250 ml
6		G		24 h	250 ml
7		P		14 d	250 ml
8		P		24 h	500 ml
9		G		24 h	500 ml
10		G		3 d	1 L
11		G		24 h	250 ml
12		G		7 d	250 ml
13	a	G		48 h	500 ml

14		G		2d	500 ml
1	G	P			
2	0~5°C				

1

a)

b)

c)

d)

e)

f)

g)

2

a)

• 2 L

• 7 L

b) /

• ±0.1 m

• 10 m

•

c) ± 10%

d) -0.05 MPa

e) HJ/T 372 HJ/T 91

B.

2017 12 28

HJ 915-2017

2014 12 23

2015 1 1

HJ 731-2014

HJ/T 354-2007

3

3

pH		0~14	—	—	±0.1	—	±0.2	±0.1

°C		-5~50	—	—	± 0.2	—	± 0.2	—
mg/L		0~50	—	—	± 0.3	—	± 0.3	± 0.3
μs/cm		0~100	—	± 1%	± 1%	—	±0.2	± 1%
mg/L		0~5	0.1	± 5%	± 10%	1%	± 10%	± 10%
^a μg/L		0~200	0.3	± 15%	± 10%	0.1%	± 10%	± 10%
	—	—		± 10%	± 10%	± 1%	± 10%	± 10%
GB 3838		I						

1)

a)

5

pH

a

b)

2)

a)

b)

c)

2 h

d)

5 MΩ

e)

50 Hz 1500 V

1 min

f)

8

6.6

6.6.1

6.6.2

CCS

2016 " "

14 mm 98 kPa
1 m 0.1 m/s 30 s
3 min

6.6.3

5.2.2.5

1

3

2

3

6.6.4

/

/

HJ/T 372-2007

HJ 915-2017

HJ 731-2014

HJ/T 354-2007

1 /

2 /

3 /
/

3

a)

V_1 3 1 ΔV 3

V_2 3

$$\Delta V = \frac{|V_2 - V_1|}{V_1} \times 100\% \quad 1$$

ΔV —

V_1 — ml

V_2 — ml

b)

-0.1~0 MPa

4

pH				—	
	—	—		—	
mg/L	—				
$\mu\text{s/cm}$	—	0.01 mol/L KCl	0.01 mol/L KCl		0.03 mol/L KCl
mg/L	3-5	50%	50%		80%
^a $\mu\text{g/L}$	3-5	50%	50%		80%
	3-5	50%	50%		80%

4

a)

4

8

2

DL

$$DL = 2.998 \times \sqrt{\frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2} \quad 2$$

DL —
 x_i — i
 \bar{x} —
 n —

b)

3 6

4

6

$$S_r = \frac{\sqrt{\frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2}}{\bar{x}} \times 100\% \quad 3$$

S_r —
 x — 6
 n — 6
 x_i — i

x_i 3 x_0 4 24 h 1 h
 x_0 6 7

RD

$$RD = x_i - x_0 \quad 6$$

RD —

x_i — i i 3 mg/L

x_0 — 3 mg/L

$$RD = \frac{x_i - x_0}{A} \times 100\% \quad 7$$

RD —

x_i — i i 3 mg/L

x_0 — mg/L

A — mg/L

e)

\bar{a} 8 10 9 \bar{A} 5 10 min

$$\bar{A} = \frac{\sum_{i=1}^n |X_i - \bar{B}|}{n\bar{B}} \times 100\% \quad 8$$

$$\bar{a} = \frac{\sum_{i=1}^n |X_i - \bar{B}|}{n} \quad 9$$

\bar{A} —

\bar{a} —

X_i — i L

\bar{B} —

n —

i —

5

pH		GB 6920
		GB 13195
		HJ 506

		HJ 535
a		HJ 897

6.6.5

GB 4943.1

6.6.6

GB 17799

6.7

GB/T 20000.1-2014

1

2

2

1

2

a)

b)

c)

3

a)

b)

c)

d)

e)

1

6.8

1

GB/T 13384

2

3

6.9

1

2

7

1	"	"	"	"	"	"	"
"	"	"	"	"	"	"	"
2	"	"	"	"	"	"	"
"	"	"	"	"	"	"	"
	200 kg		200 kg				
	200 kg						
3	"	"	"	"	"	"	"
	500 t		500 t			20 m	
	20 m					500 t	
4	"	"	"	"	"	"	"
	CCS						
	"	"	"	"	"	"	"
"	"	"	"	"	"	"	"
5	"	"	"	"	"	"	"
	CCS						
	"	"	"	"	"	"	"
9	"	"	"	"	"	"	"
	"	"	"	"	"	"	"
	"	"	"	"	"	"	"
6	"	"	"	"	"	"	"
"	"	"	"	"	"	"	"
	5	"	"	"	"	4	" 2

6 " "

8

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